

By  
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## 8- Frequency Response :-

There are two methods of analysis of systems to determine certain properties. If a time signal like step and ramp are used to excite the system and its "time response" or "time domain analysis." If sinusoidal signal of variable frequency is used to excite the system and the magnitude and phase of the steady state output from the system is measured we call it "frequency response analysis" or "frequency domain analysis".

### 8-1 Bode plot :-

One of the important representations of the sinusoidal transfer function is a Bode plot. In this type of representation the magnitude of  $G(j\omega)$  in db, i.e., ~~20 log~~  $20 \log |G(j\omega)|$  is plotted against 'log  $\omega$ '. Similarly phase angle of  $G(j\omega)$  is plotted against 'log  $\omega$ '.

The transfer function  $G(j\omega)$  can be written as

$$G(j\omega) = |G(j\omega)| e^{j\phi(\omega)}$$

Where  $\phi(\omega)$  is the angle of  $G(\omega)$ ,  $|G(j\omega)|$  is the magnitude

The open loop transfer function begin in time constant form as,

$$G(s) = \frac{K(1+sT_a)(1+sT_b)}{s^r(1+sT_1)(1+sT_2)\dots [1+2\delta \frac{s}{\omega_n} + \frac{s^2}{\omega_n^2}]}$$

Replacing  $s \rightarrow j\omega$

$$G(j\omega) = \frac{K(1+j\omega T_a)(1+j\omega T_b)}{(j\omega)^r(1+j\omega T_1)(1+j\omega T_2)\dots [1+2\delta \frac{j\omega}{\omega_n} + (\frac{j\omega}{\omega_n})^2]}$$

$$|G(j\omega)| = \frac{K |1+j\omega T_a| |1+j\omega T_b| \dots}{|\omega|^r |1+j\omega T_1| |1+j\omega T_2| \dots \left[ |1+2\delta \frac{j\omega}{\omega_n} + (\frac{j\omega}{\omega_n})^2| \right] \dots}$$

Taking  $20 \log \text{of } |G(j\omega)|$

$$\begin{aligned} 20 \log |G(j\omega)| &= 20 \log K + 20 \log |1+j\omega T_a| + 20 \log |1+j\omega T_b| \\ &\quad + \dots - 20 \log \omega^r - 20 \log |1+j\omega T_1| - 20 \log |1+j\omega T_2| \\ &\quad \dots - 20 \log \left[ |1+2\delta \frac{j\omega}{\omega_n} + (\frac{j\omega}{\omega_n})^2| \right] \end{aligned}$$

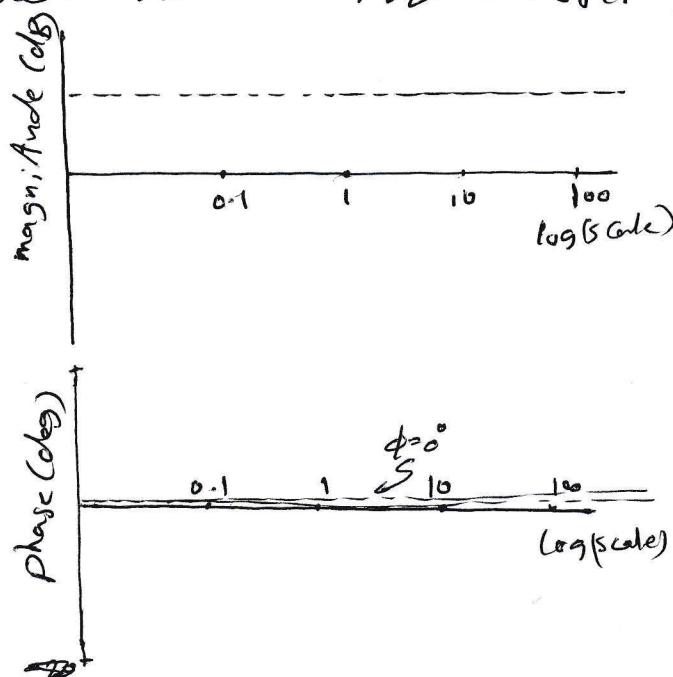
phase angle of  $G(j\omega)$  is given by

$$\begin{aligned} \phi(\omega) &= \tan^{-1} \omega T_a + \tan^{-1} \omega T_b + \dots \\ &\quad - r(90) - \tan^{-1} \omega T_1 - \tan^{-1} \omega T_2 - \tan^{-1} \frac{2\delta \omega_n}{\omega_n^2 - \omega^2} \end{aligned}$$

let us draw Bode plot for each term in the transfer function  $G(s) H(s)$ .

a) for  $K \Rightarrow 20 \log(K)$

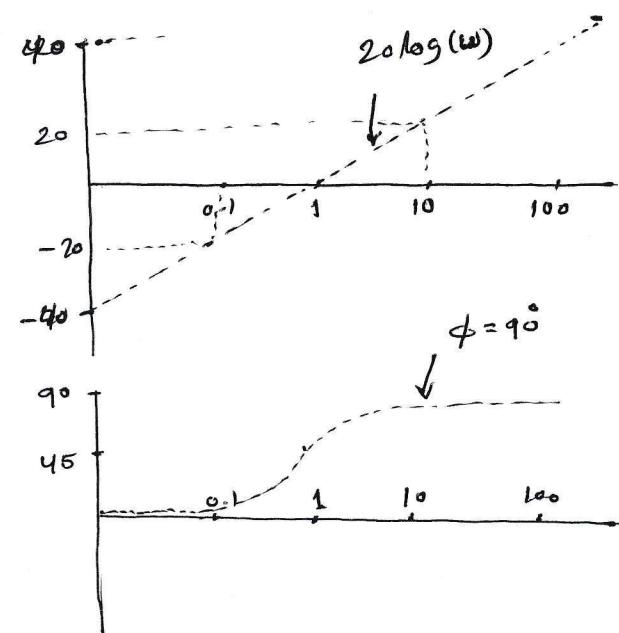
$$\phi = 0^\circ$$



b) Zero at the frequency  $j\omega$  with origin  $s$

$$|j\omega| = 20 \log(\omega)$$

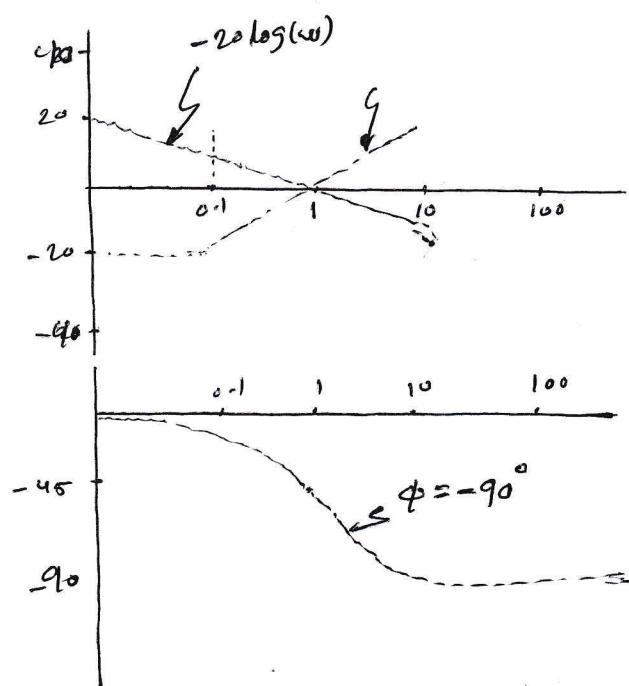
$$\phi = 90^\circ$$



c) pole at the frequency  $j\omega$  with origin  $s$

$$\frac{1}{|j\omega|} = -20 \log(\omega)$$

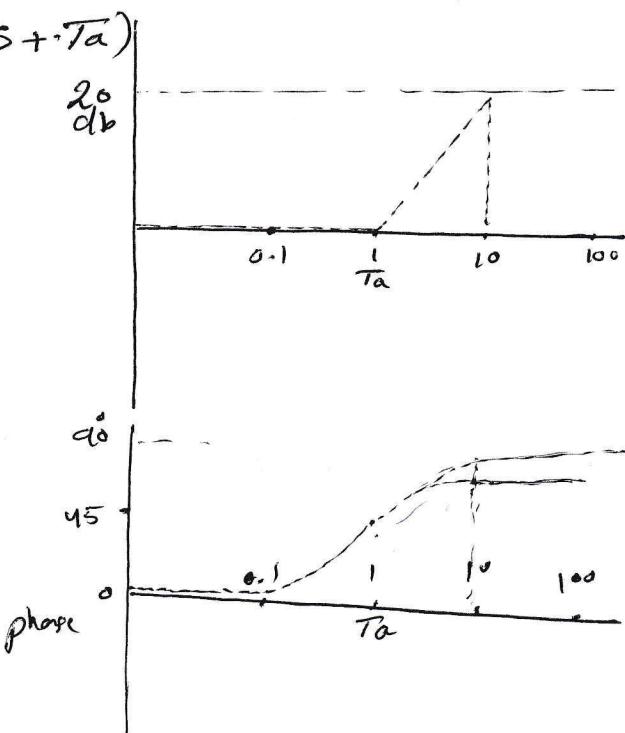
$$\phi = -90^\circ$$



d) zero at factor of the form  $(s + Ta)$

$$|j\omega + Ta| = 20 \log \sqrt{\omega^2 + Ta^2}$$

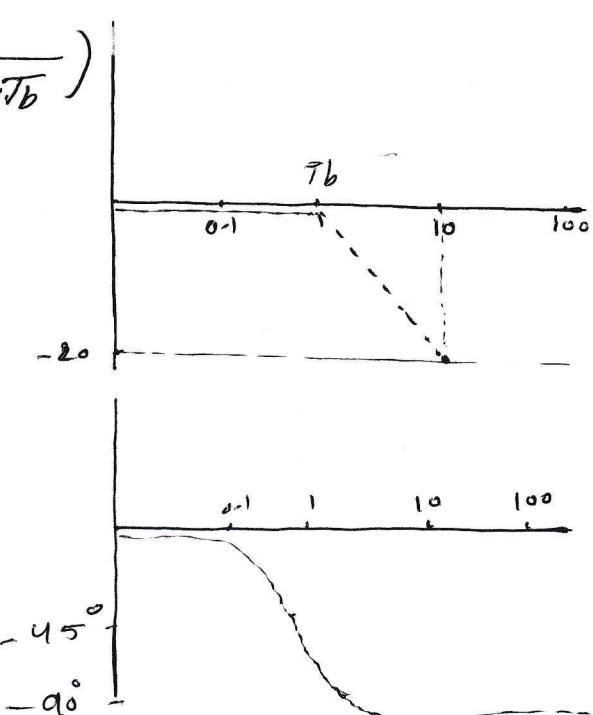
$$\phi = \tan^{-1}$$



e) pole at factor of the form  $\left(\frac{1}{s + Tb}\right)$

$$\frac{1}{|j\omega + Tb|} = -20 \log \sqrt{\omega^2 + Tb^2}$$

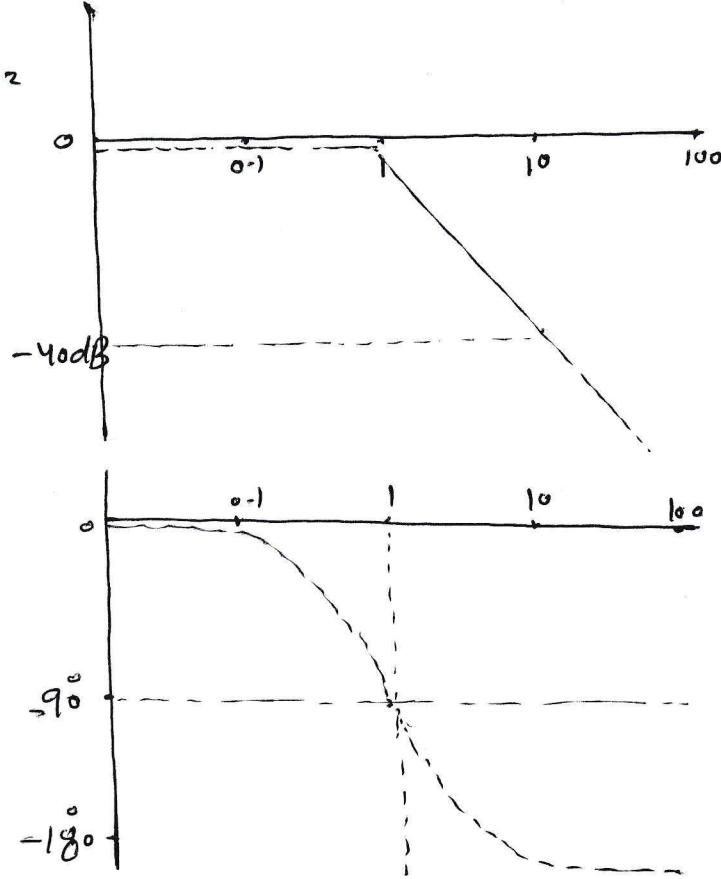
$$\phi = -\tan^{-1}$$



f) Double pole,  $G(s) = \frac{1}{(s+a)^2}$

$$\left| \frac{1}{j\omega + a} \right| = 20 \log \sqrt{\omega^2 + a^2}$$

$$\phi = -2 \tan^{-1} \frac{\omega}{a}$$



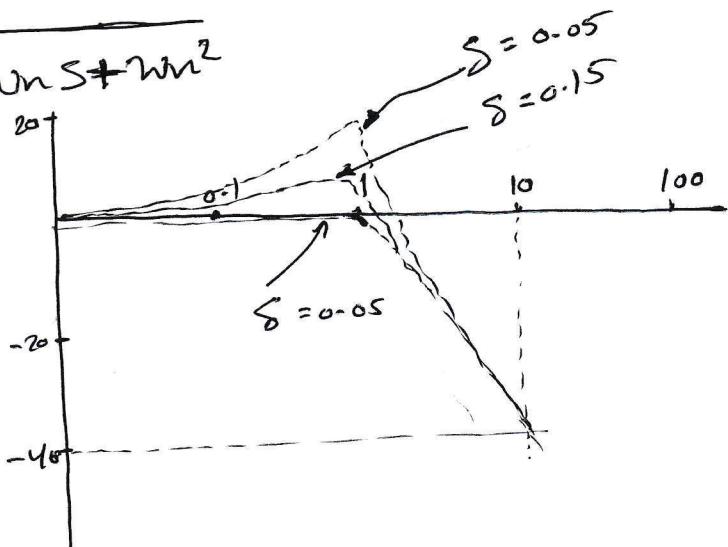
g) Second order undamped response.

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

for magnitude  $|G(j\omega)|$

~~20 log~~ for  $\omega = \omega_n$

$$\Rightarrow 20 \log \frac{1}{2\zeta} \text{ dB}$$



for  $\omega \ll \omega_n \Rightarrow 0 \text{ dB}$

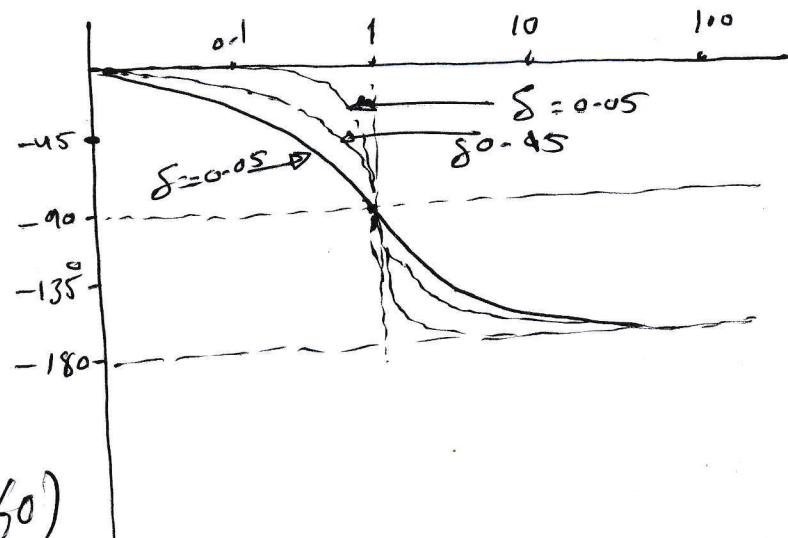
for  $\omega \gg \omega_n \Rightarrow -40 \text{ dB}$

for phase  $|G(j\omega)|$

$$\omega = \omega_n = -90^\circ$$

$$\omega \ll \omega_n \Rightarrow \phi = 0^\circ$$

$$\omega \gg \omega_n \Rightarrow \phi = -180^\circ$$



(160)

Ex obtain the Bode plot of the system given by the transfer function

$$G(s) = \frac{1}{2s+1}$$

by converting  $s \rightarrow j\omega$

$$G(j\omega) = \frac{1}{2j\omega + 1}, \quad \omega = \frac{1}{2}, \text{ the break point or corner frequency}$$

- for  $\omega \ll \frac{1}{2} \Rightarrow G(j\omega) = 1 \Rightarrow 20 \log |G(j\omega)| = 20 \log(1) = 0$

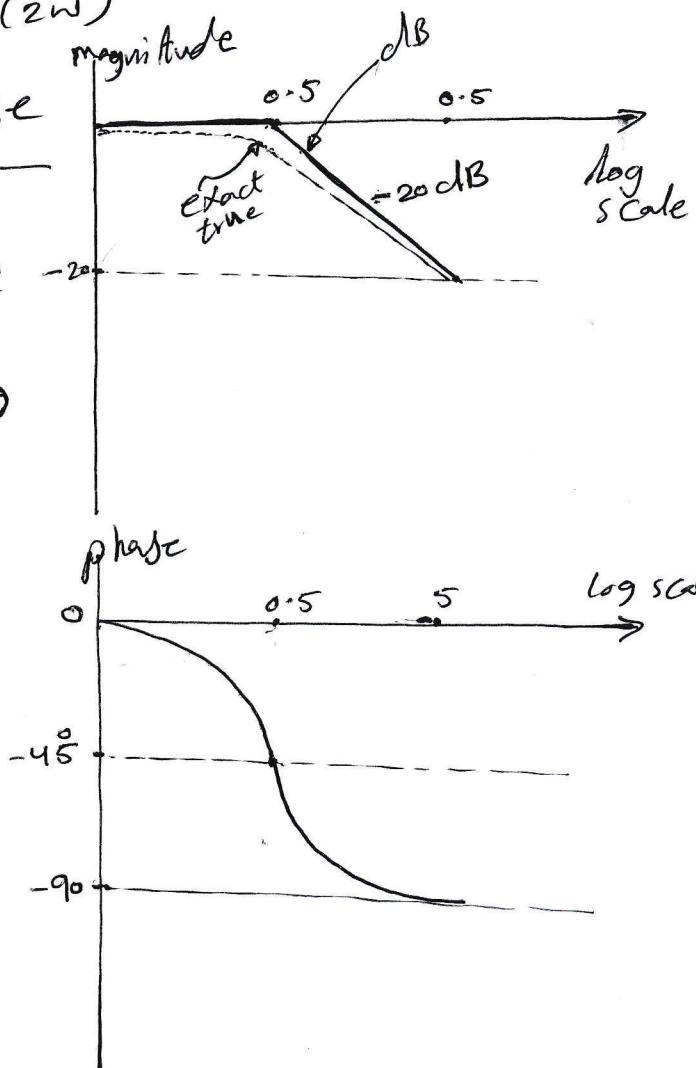
- for  $\omega \gg \frac{1}{2} \Rightarrow G(j\omega) = \frac{1}{2j\omega} \Rightarrow 20 \log |G(j\omega)|$

$$20 \log |G(j\omega)| = 20 \log \left| \frac{1}{2j\omega} \right| = 20 \log(1) - 20 \log(2\omega) = -20 \log(2\omega)$$

$$= 20 \log \left( 0.5 / \sqrt{\omega^2 + 0.5^2} \right)$$

$$\phi = 0 - \tan^{-1}(2\omega) = -\tan^{-1}(2\omega)$$

$\omega$	magnitude	phase
0.05	0	-0.043
0.5	0	-3.01
5	-20 dB	-20.043
10		-90



Ex obtain the bode plot of the system given by the transfer function

$$G(s) = \frac{4}{s^2 + s + 4}$$

Replacing  $s = j\omega$  in the transfer function.

$$G(j\omega) = \frac{4}{(j\omega)^2 + j\omega + 4} = \frac{\omega n^2}{(\frac{j\omega}{\omega_n})^2 + 2\delta\omega_n j + \omega_n^2}$$

$$\omega n^2 = 4 \Rightarrow \omega n = 2$$

$$2\delta\omega_n = 1 \Rightarrow \delta = \frac{1}{2}$$

$$G(j\omega) = \frac{1}{(\frac{j\omega}{\omega_n})^2 + 2\delta(\frac{j\omega}{\omega_n}) + 1} = \frac{1}{(\frac{j\omega}{2})^2 + 0.5(\frac{j\omega}{2}) + 1}$$

the break point or corner frequency is  $\omega = \omega_n$ ,

at  $\omega = \omega_n$ , for small values of  $\omega$ ,

$$G(j\omega) \approx 1 \Rightarrow 20 \log |G(j\omega)| = 20 \log (1) = 0$$

- For larger values of  $\omega$ ,  $\omega \gg \omega_n$ , we get

$$G(j\omega) \approx \frac{1}{(\frac{j\omega}{\omega_n})^2} = \frac{1}{(\frac{j\omega}{2})^2}$$

$$20 \log |G(j\omega)| = 20 \log \left( \frac{1}{(\frac{\omega}{\omega_n})^2} \right) = 20 \log (1) - 20 \log \left( \frac{\omega}{\omega_n} \right)^2$$

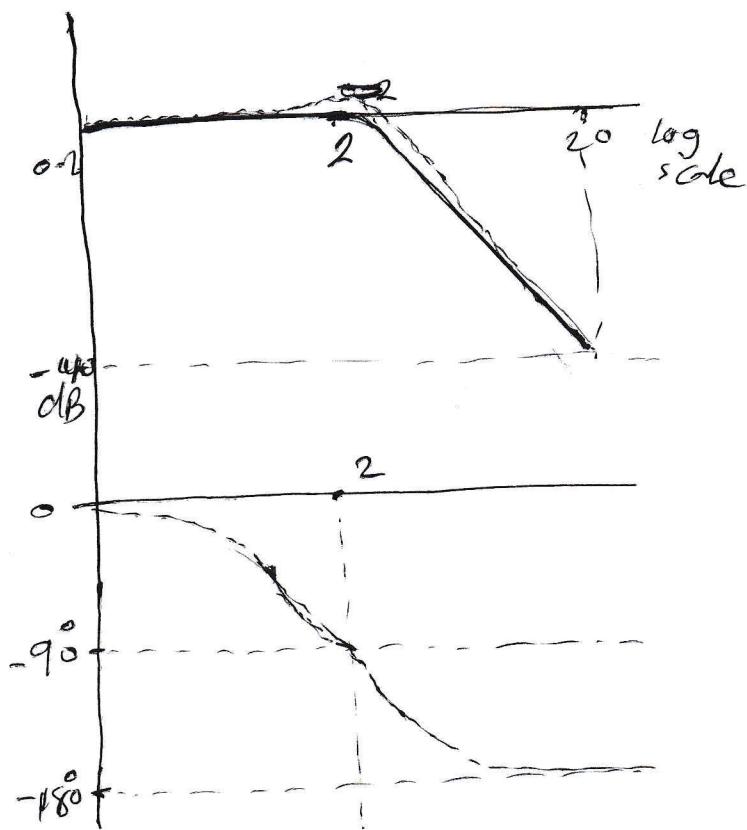
$$= -40 \log \frac{\omega}{\omega_n} = -40 \log \frac{\omega}{2}$$

$$\phi = \omega - \tan^{-1}$$

$$\omega = 0.2 \Rightarrow \phi = 0^\circ$$

$$\omega = 2 \Rightarrow \phi = 90^\circ$$

$$\omega = 20 \Rightarrow \phi = -180^\circ$$



Ex Plot the Bode magnitude and phase for the system with transfer function.

$$G(s) = \frac{2000(s+0.5)}{s(s+10)(s+50)}$$

① by converting  $s = j\omega$

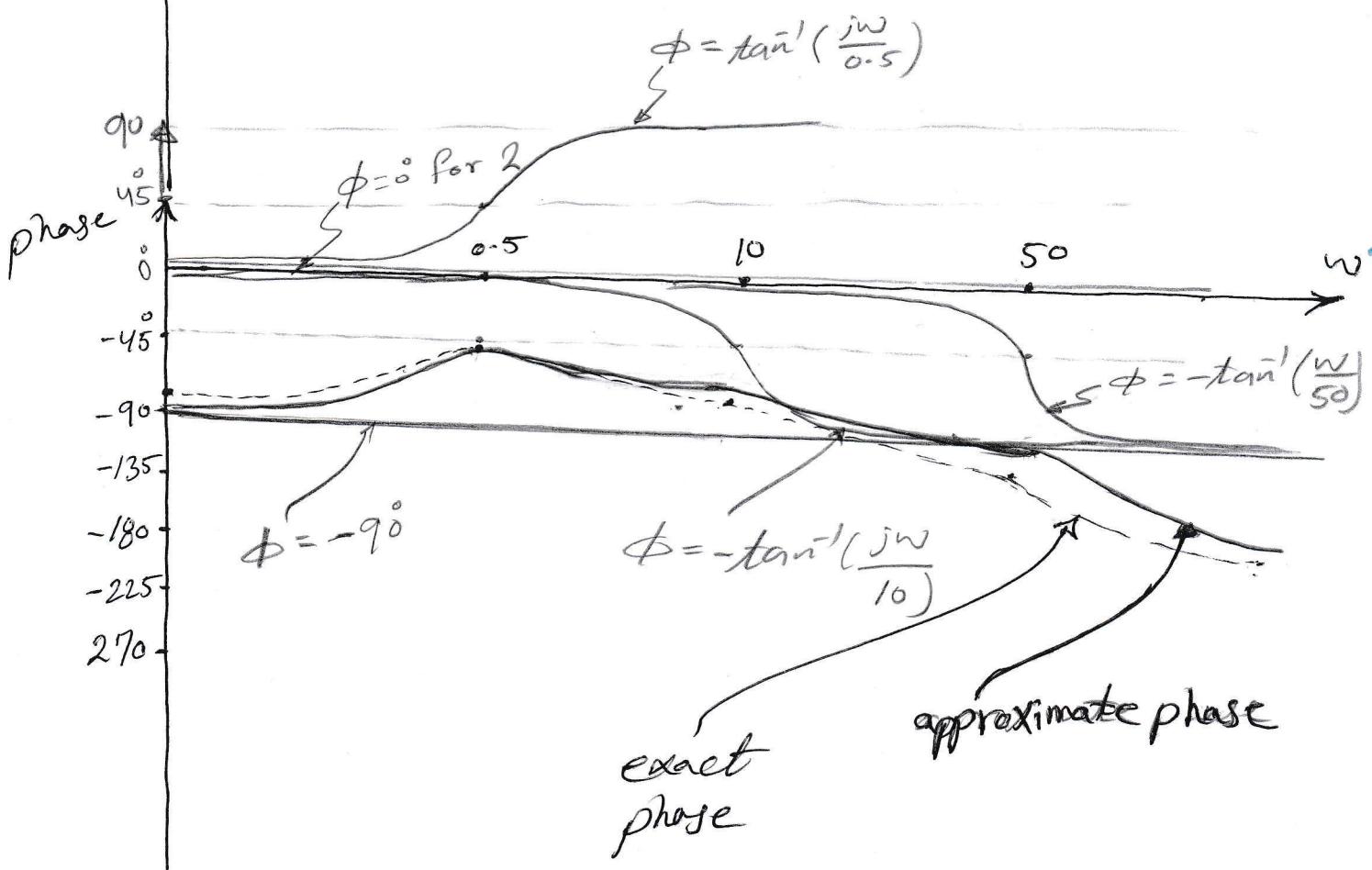
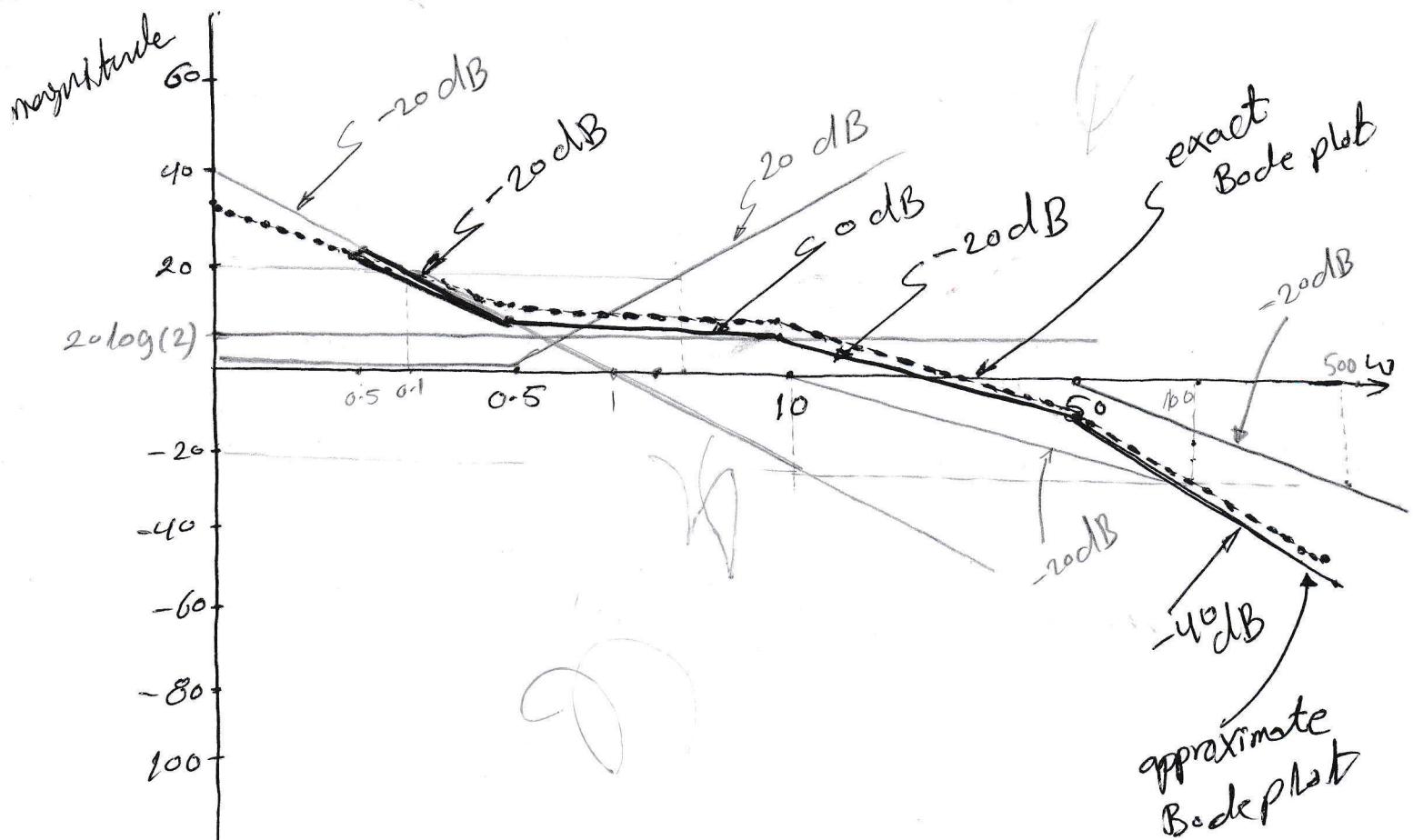
$$G(j\omega) = \frac{2000(j\omega + 0.5)}{(j\omega)(j\omega + 10)(j\omega + 50)} = \frac{2 \left( \frac{j\omega}{0.5} + 1 \right)}{j\omega \left( \frac{j\omega}{10} + 1 \right) \left( \frac{j\omega}{50} + 1 \right)}$$

$$|Q(j\omega)| = 20 \log \left[ \frac{2000 * (\sqrt{\omega^2 + 0.5^2})}{\omega * (\sqrt{\omega^2 + 100}) * (\sqrt{\omega^2 + 50^2})} \right]$$

<u><math>\omega</math></u>	Magnitude		phase
	Exact	approximat	
0.05	32.0841	32	-84.63°
0.5	15		-48.43°
10	8.8714		-59.1723°
50	-5.1184		-124.26°
500	-41.983		-173.2009°

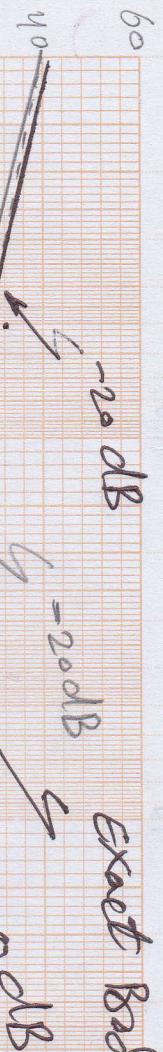
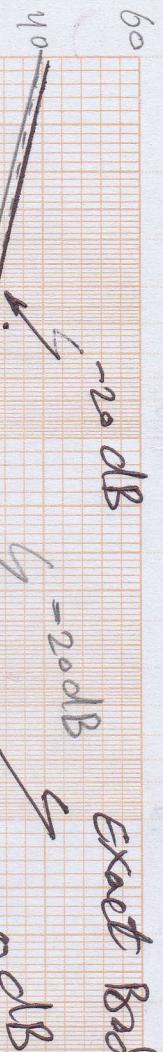
$$\phi = 0 + \tan^{-1} \frac{\omega}{0.5} - 90 - \tan^{-1} \frac{\omega}{10} - \tan^{-1} \frac{\omega}{50}$$

(164)



exact Bode plot

approximate Bode plot



$$\phi = \tan^{-1} \left( \frac{\omega}{0.5} \right)$$

exact phase

$$\phi = -\tan^{-1} \left( \frac{\omega}{10} \right) \quad \phi = -\tan^{-1} \left( \frac{\omega}{50} \right)$$

approximate  
phase



Ex Draw the frequency response of the system given by the transfer function.

$$G(s) = \frac{10}{s(s^2 + 0.4s + 4)}$$

$$G(s) = \frac{\frac{10}{4}}{s\left(\frac{s^2}{4} + 0.2 \cdot \frac{3}{2} + 1\right)}$$

by Replacing  $s=j\omega$  in the transfer function

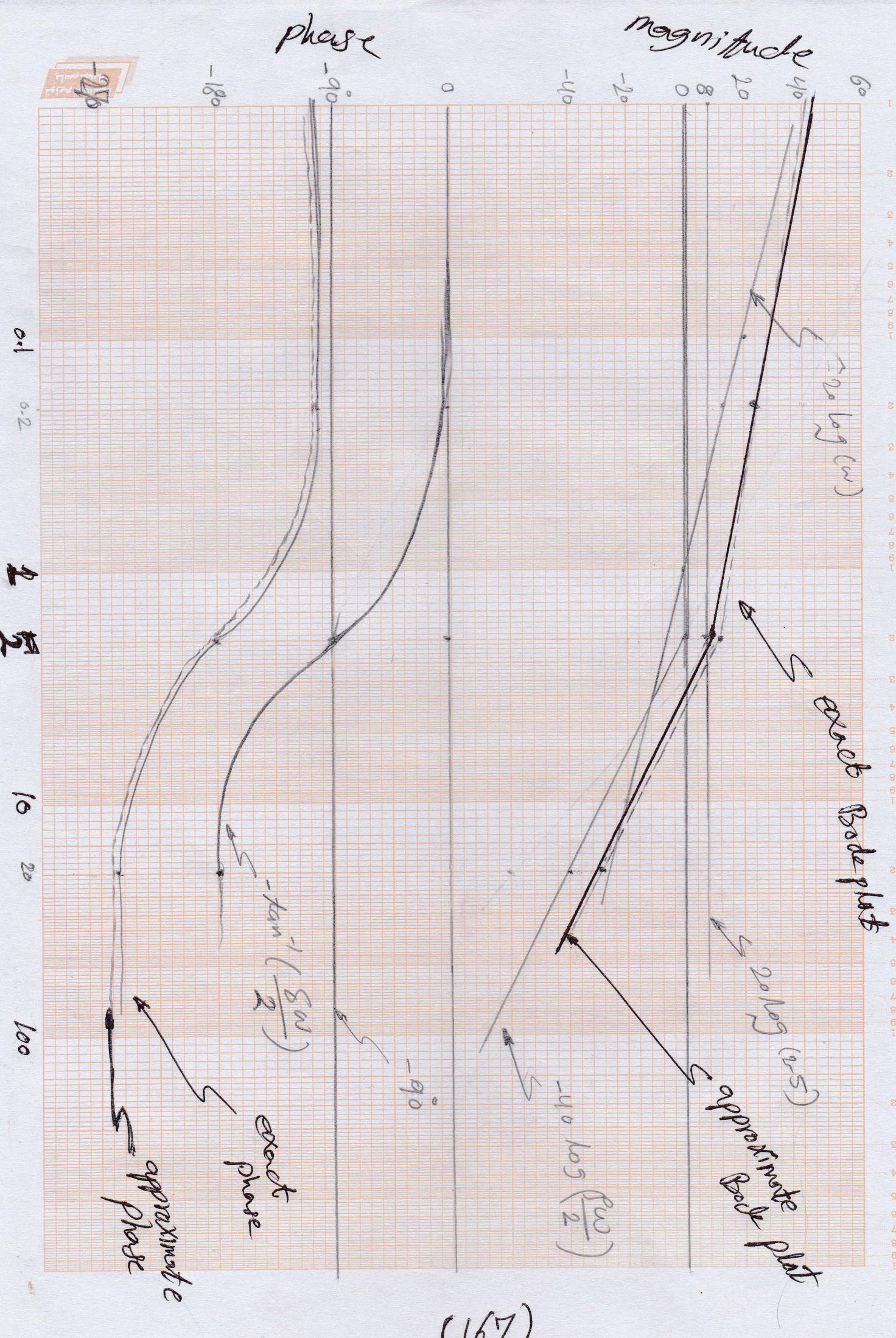
$$G(j\omega) = \frac{10}{4} \frac{1}{j\omega \left( \left(\frac{j\omega}{2}\right)^2 + 0.2 \left(\frac{j\omega}{2}\right) + 1 \right)}$$

The corner frequency is  $\omega_c = 2$

$$|G(j\omega)| = 20 \log \left[ \frac{10/4}{\omega \sqrt{\left(\frac{\omega}{2}\right)^2 + \left(\frac{0.4\omega}{2}\right)^2}} \right]$$

$$\text{phase} = 0 - 90^\circ - 2 \tan^{-1} \left( \frac{\omega}{2} \right)$$

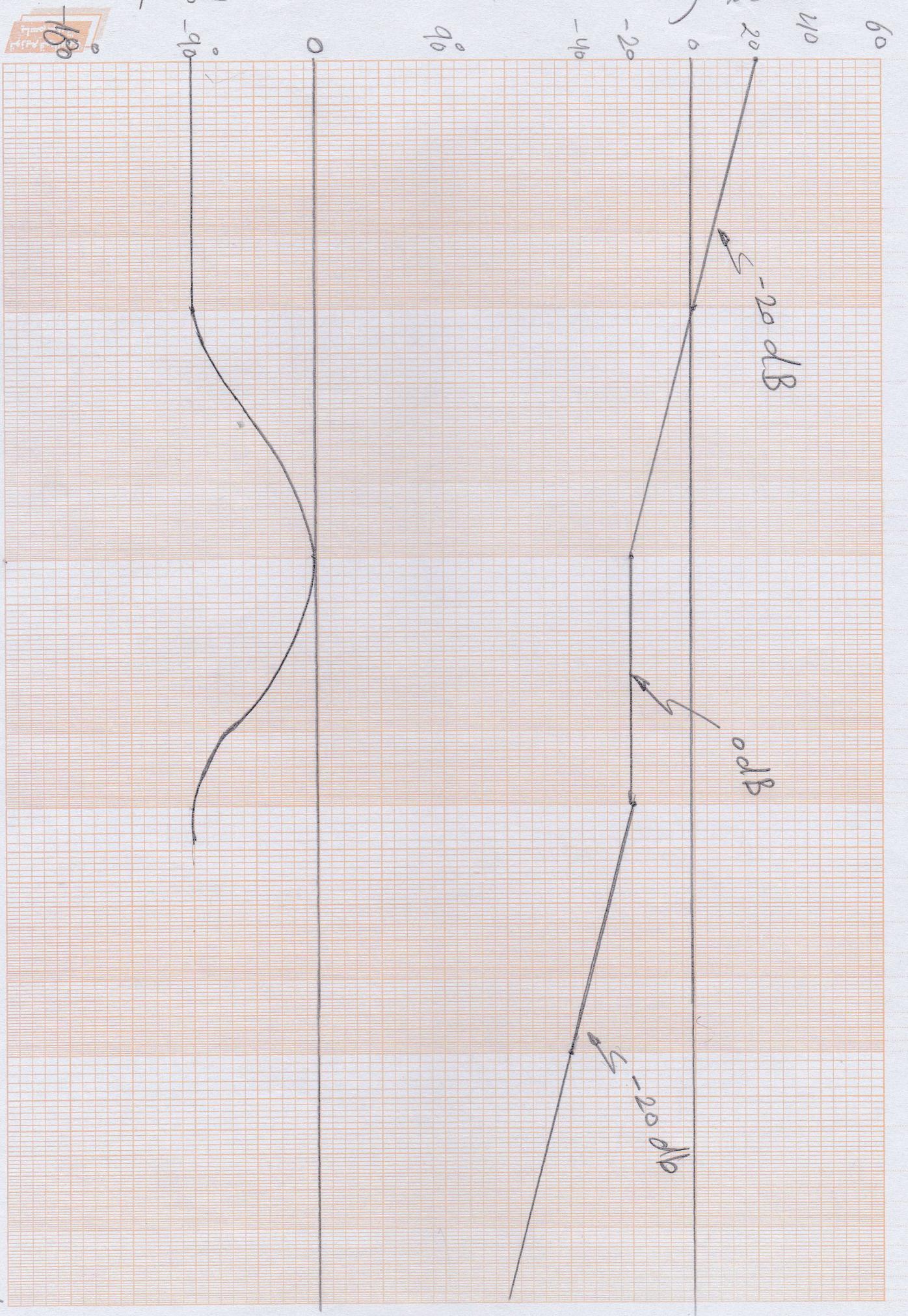
<u><math>\omega</math></u>	Magnitude	Phase
0.2	22.02	$-101.4212^\circ$
2	15.9175	$-180^\circ$
20	$-57.9759$	$-258.5788^\circ$



EX Sketch the bode plot of the transfer function

$$H(s) = \frac{100(s+10)}{s^2 + 1000s}$$

$$\begin{aligned} H(j\omega) &= \frac{100(j\omega + 10)}{(j\omega)^2 + 1000j\omega} \\ &= \frac{100(j\omega + 10)}{j\omega(j\omega + 1000)} \\ &= \frac{100 \times 10 \left( \frac{j\omega}{10} + 1 \right)}{1000 j\omega \left( \frac{j\omega}{1000} + 1 \right)} \\ &= \frac{\left( \frac{j\omega}{10} + 1 \right)}{j\omega \left( \frac{j\omega}{1000} + 1 \right)} \end{aligned}$$



(169)